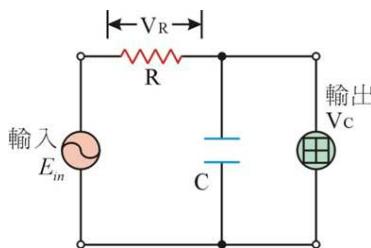
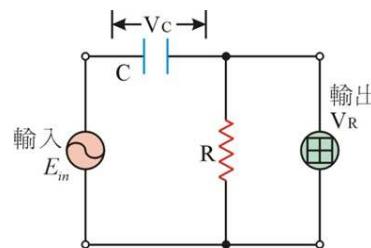




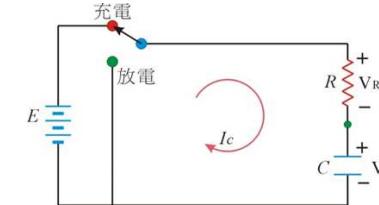
# 實驗05： 微分器與積分器



1



## RC電路：充電過程



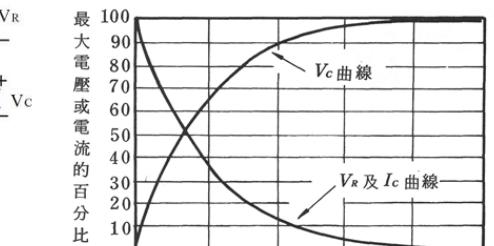
$$E = V_R + V_C = I_C R + \frac{Q}{C}$$

$$I_C = \frac{dQ}{dt}$$

$$E = R \frac{dQ}{dt} + \frac{Q}{C}$$

$$CR \frac{dQ}{dt} + Q - CE = 0$$

$$Q = CE(1 - e^{\frac{-t}{RC}})$$

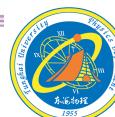


$$I_C = \frac{dQ}{dt} = \frac{E}{R} e^{\frac{-t}{RC}}$$

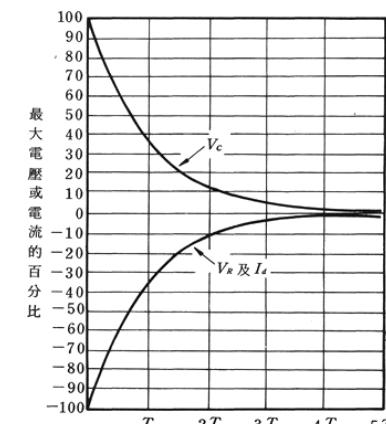
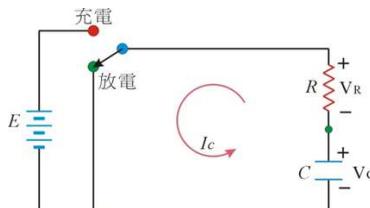
$$V_R = I_C R = E e^{\frac{-t}{RC}}$$

$$V_C = E - V_R = E(1 - e^{\frac{-t}{RC}})$$

2



## RC電路：放電過程

當電容充飽後  $\bullet$   $V_C = E$ 

$$V_R + V_C = I_C R + \frac{Q}{C} = 0$$

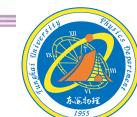
$$Q = CE e^{\frac{-t}{RC}}$$

$$I_C = \frac{dQ}{dt} = -\frac{E}{R} e^{\frac{-t}{RC}}$$

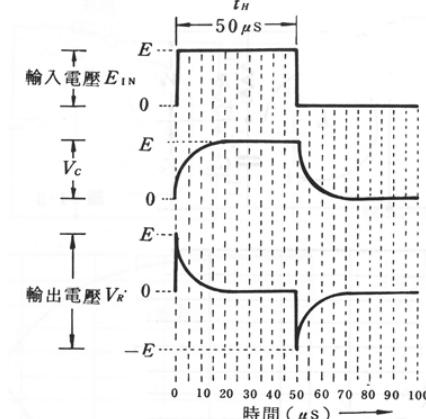
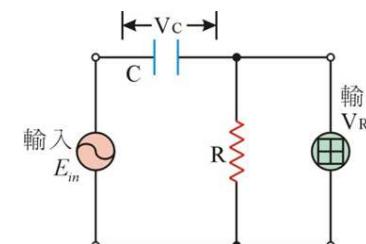
$$V_R = I_C R = -E e^{\frac{-t}{RC}}$$

$$V_C = E - V_R = E e^{\frac{-t}{RC}}$$

3

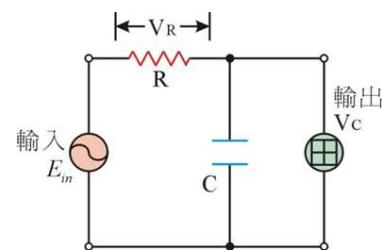


## 微分電路

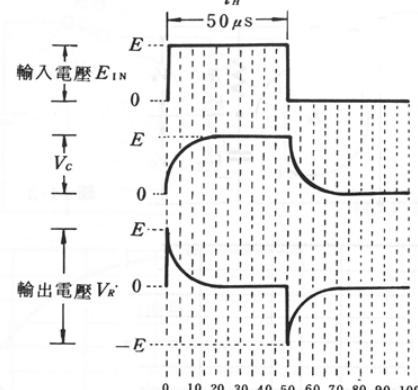


4

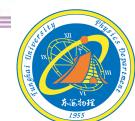
積分電路



- (a) 輸入波形  
(b)  $RC = 0.05 t_H$  時之輸出波形  
(c)  $RC = 0.25 t_H$  時之輸出波形  
(d)  $RC = t_H$  時之輸出波形  
(e)  $RC = 5t_H$  時之輸出波形



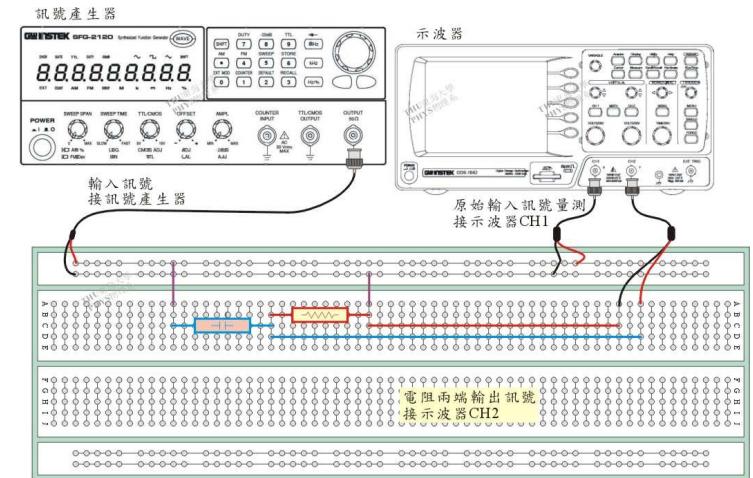
5



RC電路【【微分電路】】

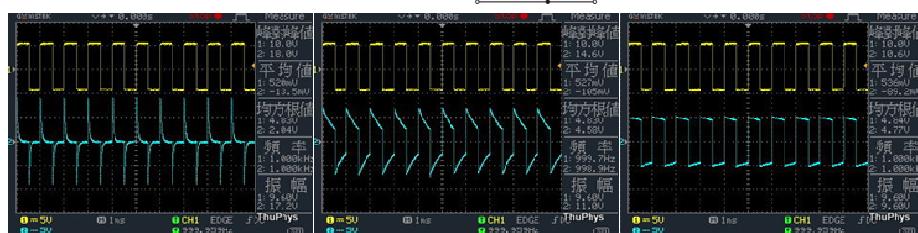
輸入：方波

輸出：R兩端

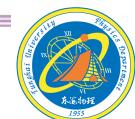


6

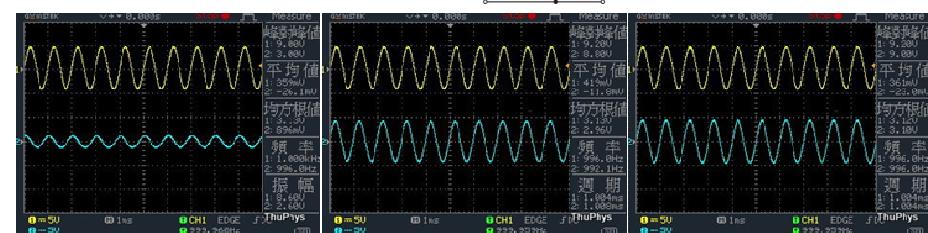
RC電路【【微分電路】】  
**C=0.01uF**  
 輸入：方波  
 輸出：R兩端



7



RC電路【【微分電路】】  
**C=0.01uF**  
 輸入：正弦波  
 輸出：R兩端

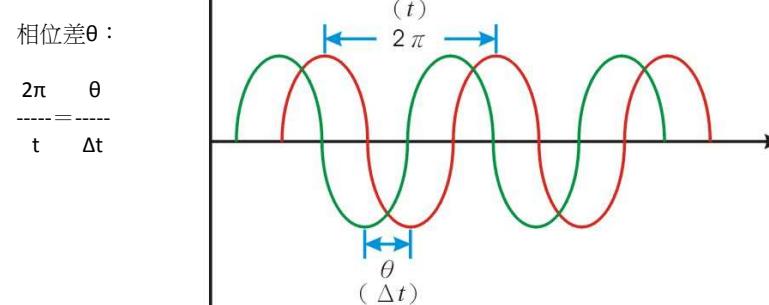
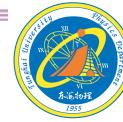


8

## RC電路【【微分電路】】C=0.01uF

輸入：正弦波  
輸出：R兩端

輸入1kHz訊號  
⌚ t=1ms

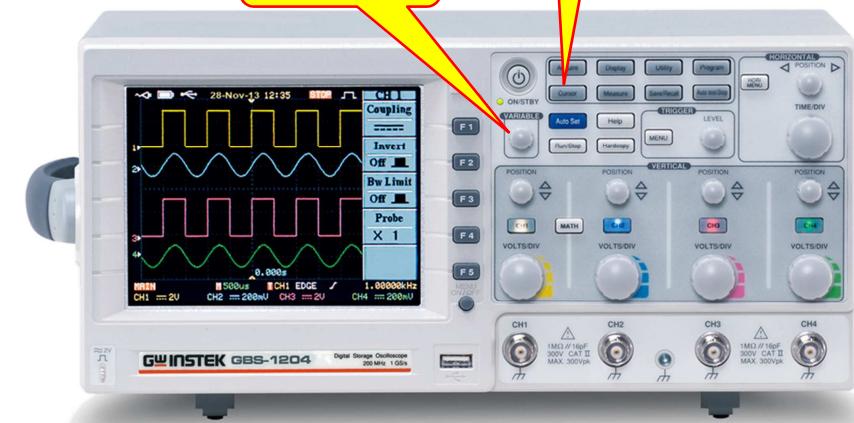


利用示波器Cursor功能，定位 $t$ 與 $\Delta t$ 位置。

## GBS1074示波器 CURSOR游標定位功能



Variable旋鈕  
改變游標位置  
Cursor

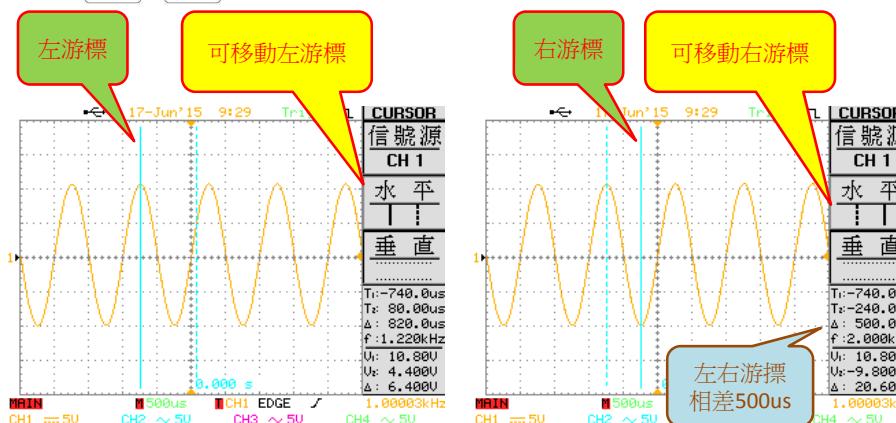


## GBS1074示波器 CURSOR游標定位功能



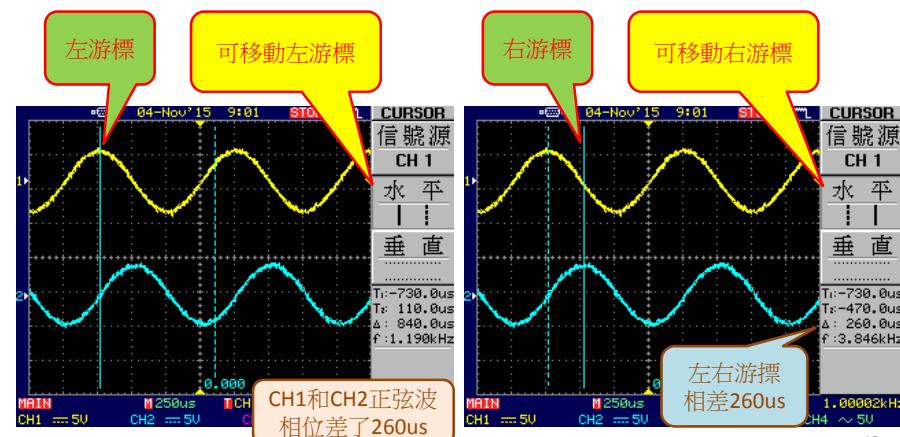
應用按鍵 Acquire Cursor Utility Program  
Display Measure SaveRecall Auto test/Stop  
Auto Set Help  
Run/Stop Hardcopy

先移動左游標  
再移動右游標  
記錄兩游標的時間差



應用按鍵 Acquire Cursor Utility Program  
Display Measure SaveRecall Auto test/Stop  
Auto Set Help  
Run/Stop Hardcopy

先移動左游標  
再移動右游標  
記錄兩游標的時間差

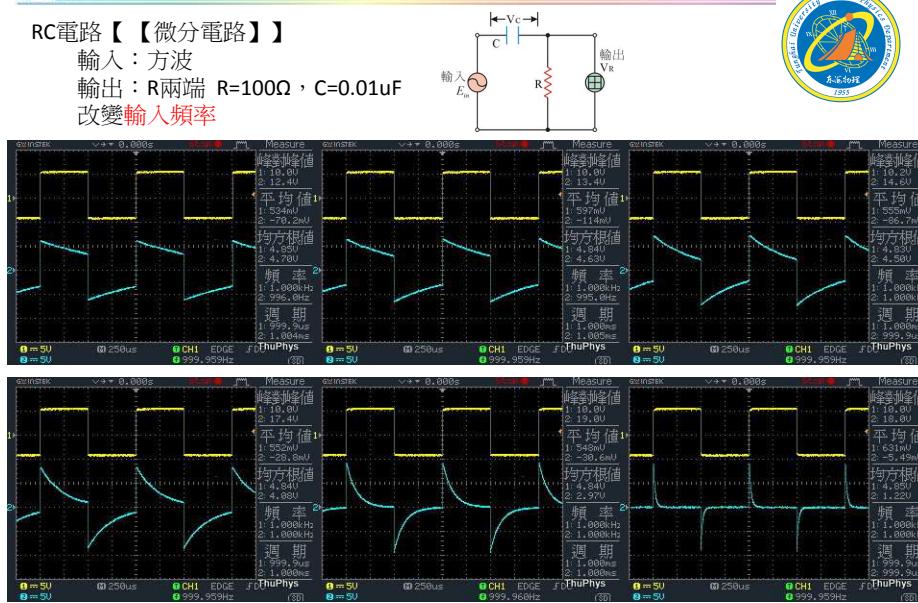


## RC電路【【微分電路】】

輸入：方波

輸出：R兩端  $R=100\Omega$ ,  $C=0.01\mu F$ 

改變輸入頻率



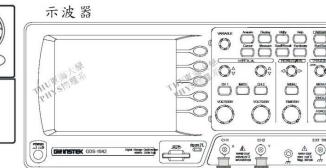
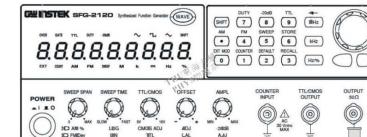
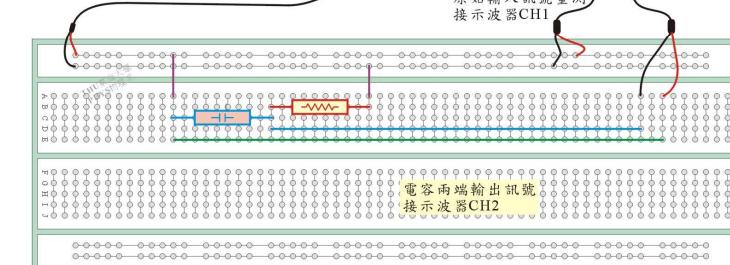
13

## RC電路【【積分電路】】

輸入：方波

輸出：C兩端

訊號產生器

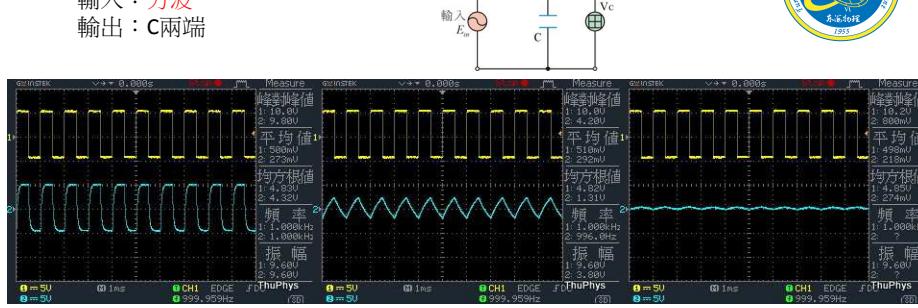
輸入訊號  
接訊號產生器

14

RC電路【【積分電路】】 $C=0.01\mu F$ 

輸入：方波

輸出：C兩端

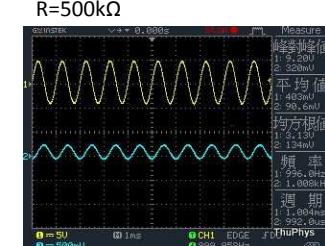
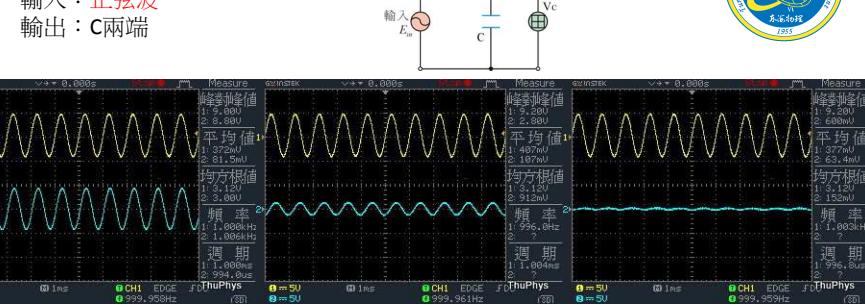


15

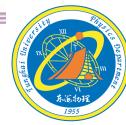
RC電路【【積分電路】】 $C=0.01\mu F$ 

輸入：正弦波

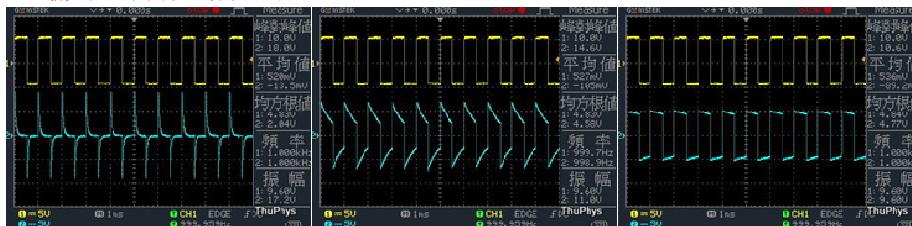
輸出：C兩端



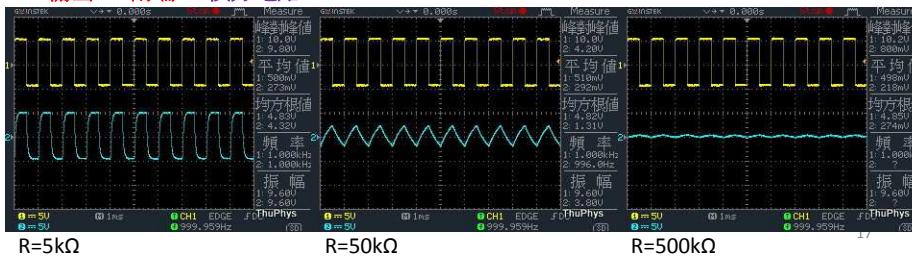
16

RC電路， $C=0.01\mu F$ ，輸入：方波

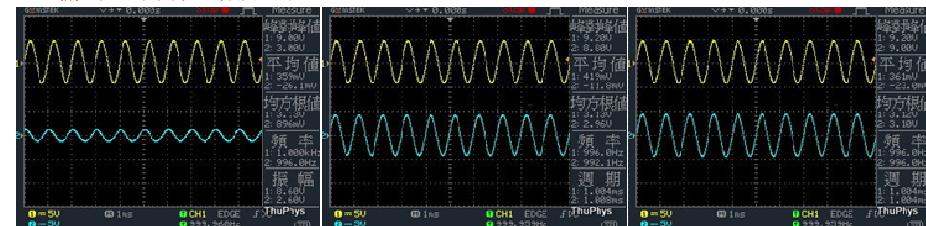
## 輸出：R兩端 微分電路



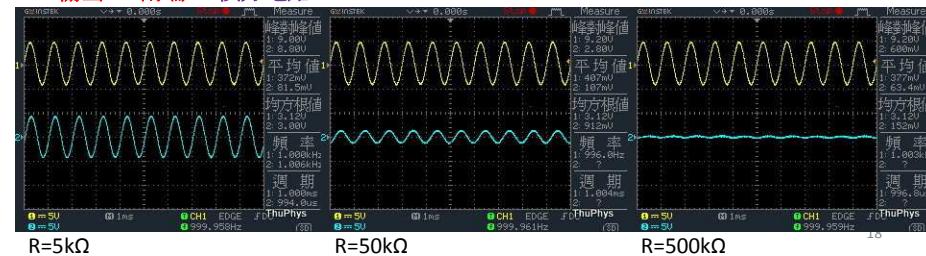
## 輸出：C兩端 積分電路

RC電路， $C=0.01\mu F$ ，輸入：正旋波

## 輸出：R兩端 微分電路



## 輸出：C兩端 積分電路



## RC電路

外加電壓為交流訊號  $V_{AC} = V_0 e^{i\omega t}$ 

$$V_{AC} = V_R + V_C = I_C R + \frac{Q}{C}$$

$$Q = Q_0 e^{i\omega t}$$

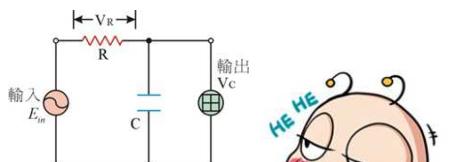
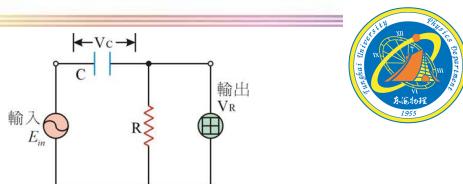
$$V_0 e^{i\omega t} = i\omega R Q_0 e^{i\omega t} + \frac{Q_0 e^{i\omega t}}{C}$$

$$Q_0 = \frac{V_0}{i\omega R + \frac{1}{C}}$$

$$V_C = \frac{Q}{C} = \left( \frac{V_0}{i\omega R + \frac{1}{C}} e^{i\omega t} \right) \frac{1}{C} = \frac{V_{AC}}{i\omega RC + 1}$$

電容器上的電壓與外加電壓 $V_{AC}$ 有相位偏移，偏移量為  $\phi = \tan^{-1} \frac{1}{\omega RC}$ 

$$\text{其弦波振幅大小也會衰減為 } |V_C| = \frac{|V_{AC}|}{\sqrt{\omega^2 R^2 C^2 + 1}}$$



## RC電路

外加電壓為交流訊號  $V_{AC} = V_0 \cos \omega t$ 

$$V_{AC} = V_R + V_C = I_C R + \frac{Q}{C}$$

$$R \frac{dQ}{dt} + \frac{Q}{C} = V_0 \cos \omega t$$

$$Q = Q_1 \cos \omega t + Q_2 \sin \omega t$$

$$\frac{dQ}{dt} = -\omega Q_1 \sin \omega t + \omega Q_2 \cos \omega t$$

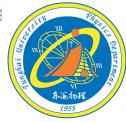
$$R(-\omega Q_1 \sin \omega t + \omega Q_2 \cos \omega t) + \frac{1}{C}(Q_1 \cos \omega t + Q_2 \sin \omega t) = V_0 \cos \omega t$$

$$\left( -\omega R Q_1 + \frac{Q_2}{C} \right) \sin \omega t + \left( \omega R Q_2 + \frac{Q_1}{C} \right) \cos \omega t = V_0 \cos \omega t$$

$$-\omega R Q_1 + \frac{Q_2}{C} = 0 \quad \rightarrow \quad Q_2 = \omega R C Q_1$$

$$\omega R Q_2 + \frac{Q_1}{C} = V_0 \quad \rightarrow \quad \omega^2 R^2 C Q_1 + \frac{Q_1}{C} = V_0$$





$$\omega^2 R^2 C Q_1 + \frac{Q_1}{C} = V_0$$

$$Q_1 = \frac{\frac{V_0}{C}}{\frac{1}{C^2} + \omega^2 R^2} = \frac{CV_0}{1 + \omega^2 R^2 C^2}$$

$$Q_2 = \frac{\omega R V_0}{\frac{1}{C^2} + \omega^2 R^2} = \frac{\omega R C^2 V_0}{1 + \omega^2 R^2 C^2} = \omega R C Q_1$$

$$\begin{aligned} Q &= Q_1 \cos \omega t + Q_2 \sin \omega t = \frac{CV_0}{1 + \omega^2 R^2 C^2} \cos \omega t + \frac{\omega R C^2 V_0}{1 + \omega^2 R^2 C^2} \sin \omega t \\ &= \frac{CV_0}{\sqrt{1 + \omega^2 R^2 C^2}} \left( \frac{1}{\sqrt{1 + \omega^2 R^2 C^2}} \cos \omega t + \frac{\omega R C}{\sqrt{1 + \omega^2 R^2 C^2}} \sin \omega t \right) \\ &= Q_0 \cos(\omega t - \phi) \end{aligned}$$

$$Q_0 = \frac{CV_0}{\sqrt{1 + \omega^2 R^2 C^2}}$$

$$\phi = \tan^{-1} \frac{1}{\omega R C}$$

21

$$V_{AC} = V_0 \cos \omega t$$

$$Q = \frac{CV_0}{\sqrt{1 + \omega^2 R^2 C^2}} \cos(\omega t - \phi)$$

$$i = \frac{dQ}{dt} = \frac{\omega C V_0}{\sqrt{1 + \omega^2 R^2 C^2}} \cos(\omega t - \phi + \frac{\pi}{2})$$

$$V_C = \frac{Q}{C} = \frac{V_0}{\sqrt{1 + \omega^2 R^2 C^2}} \cos(\omega t - \phi)$$

$$V_R = iR = \frac{\omega R C V_0}{\sqrt{1 + \omega^2 R^2 C^2}} \cos(\omega t - \phi + \frac{\pi}{2})$$

電源電壓  $V_{AC}$  領先電容器電壓  $V_C$ ，相位  $\phi$ 。電源電壓  $V_{AC}$  領先電阻器電壓  $V_R$ ，相位  $\phi - 90^\circ$ 。

$$\phi = \tan^{-1} \frac{1}{\omega R C}$$

R (kΩ)	C (uF)	$V_C$ 振幅	$V_R$ 振幅
5	0.01	0.95	0.30
50	0.01	0.30	0.95
500	0.01	0.03	1.00

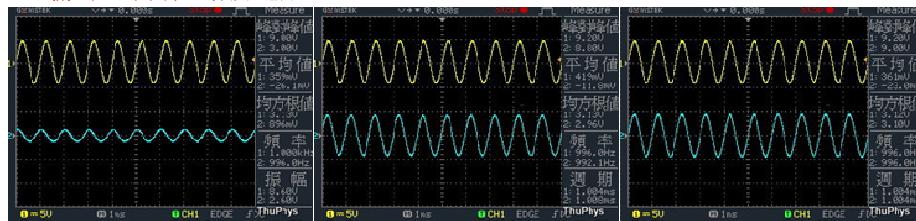
R (kΩ)	C (uF)	$V_C$ 相位差	$V_R$ 相位差
5	0.01	72.57	17.43
50	0.01	17.67	72.33
500	0.01	1.82	88.18

22

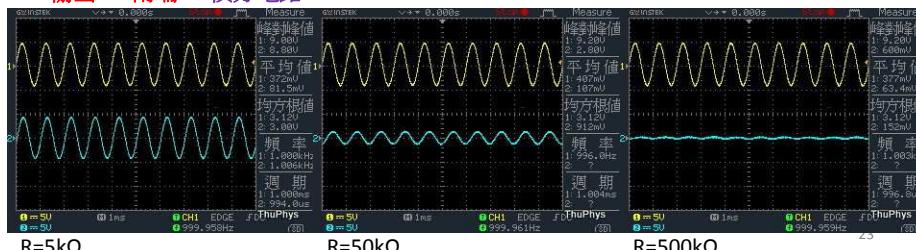
RC電路， $C=0.01\mu F$ ，輸入：正旋波

R (kΩ)	C (uF)	$V_C$ 振幅	$V_R$ 振幅
5	0.01	0.95	0.30
50	0.01	0.30	0.95
500	0.01	0.03	1.00

輸出：R兩端 微分電路



輸出：C兩端 積分電路

 $R=5k\Omega$  $R=50k\Omega$  $R=500k\Omega$ 

我們沒有最好  
只有追求更好

有空繼續補~~



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24